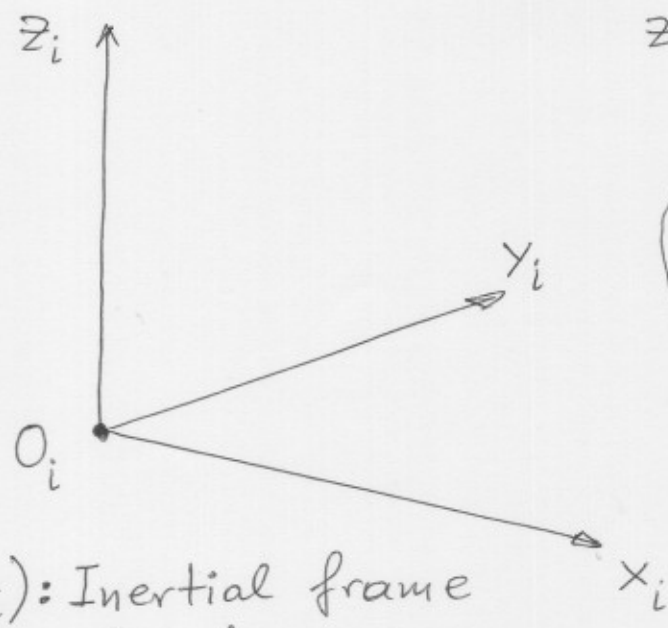
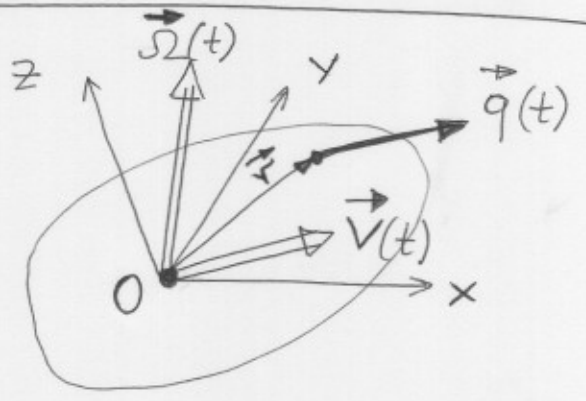


N-S equations w.r.t. moving frame

(for proof see "An Introduction to Fluid Dynamics" by G.K. Batchelor)



$(O_i x_i y_i z_i)$: Inertial frame of reference



$(Oxyz)$: Moving frame of reference

$\vec{V}(t)$: translational velocity vector of $(Oxyz)$

$\vec{\Omega}(t)$: angular velocity vector of $(Oxyz)$

$\vec{q}(t)$: flow field velocity vector w.r.t. moving frame

$$\frac{D\vec{q}}{Dt} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \vec{q} + \vec{g} + \frac{d\vec{V}}{dt} - 2\vec{\Omega} \times \vec{q} - \frac{d\vec{\Omega}}{dt} \times \vec{r} - \vec{\Omega} \times (\vec{\Omega} \times \vec{r})$$

↑ Translational acceleration of moving frame
 ↑ Coriolis
 ↑ "No name"
 ↑ Centripetal

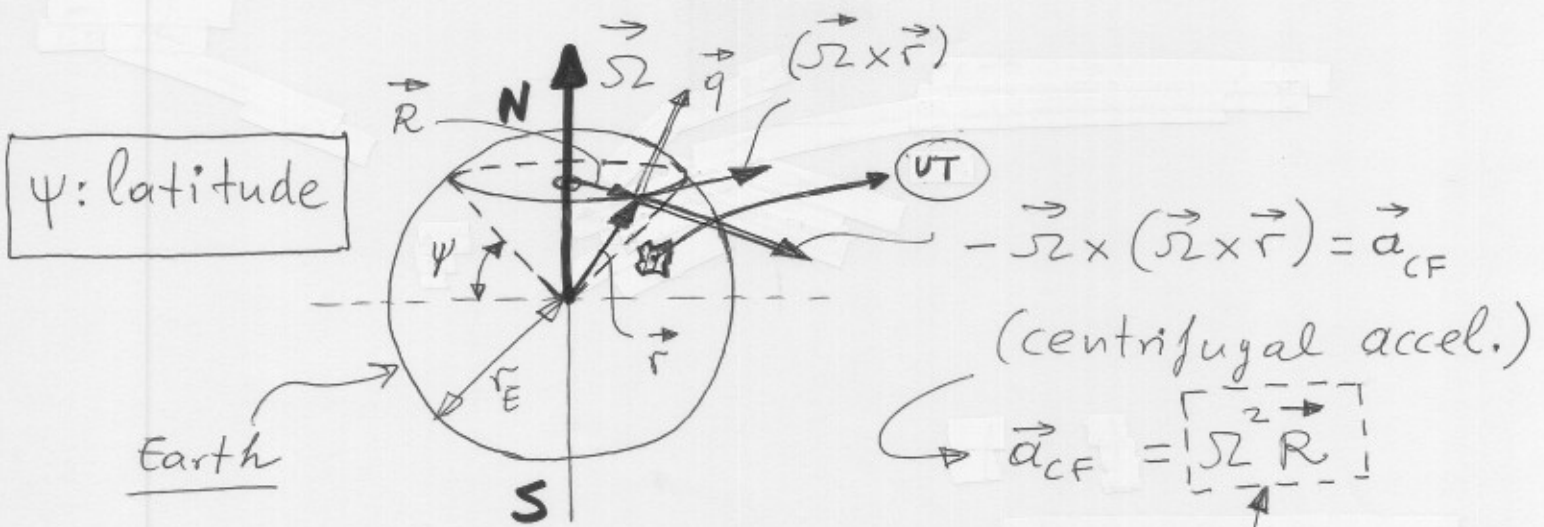
↑ Acceleration of fluid particle w.r.t. moving frame
 ↑ Additional accelerations that have been put on the RHS with the (-) sign in front

Special application: Geophysical Flows

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$$\vec{V} = 0 \quad \text{and} \quad \frac{d\vec{\Omega}}{dt} = 0$$



N-S become:

$$\frac{D\vec{q}}{Dt} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \vec{q} + \vec{g} - 2\vec{\Omega} \times \vec{q} - \vec{\Omega} \times (\vec{\Omega} \times \vec{r})$$

Assuming that \vec{q} is tangent to the earth surface (i.e. vertical velocity $w=0$) it

can be shown that N-S reduce to:
(also ignoring the centrifugal acceleration)

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f v = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u \quad (1)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + f u = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \nabla^2 v \quad (2)$$



where $f = \text{Coriolis parameter or planetary vorticity} = 2\Omega \sin \psi$

Rossby number: Ro

For small Ro \Rightarrow Coriolis effects important $Ro = U / (fL)$